



Non-destructive data fusion from ultrasonic and eddy current testing using artificial neural networks

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Context and aim

Simulated data base

Ultrasonic data

Eddy current data

Data fusion

Architecture

Input/output data

Results

Conclusion / future work

1 Context and aim

2 Simulated data base

Ultrasonic data

Eddy current data

3 Data fusion with artificial neural networks

Network architecture

Network inputs/outputs

Training and test results

4 Conclusion and future work

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Non destructive testing is widely used in many fields to detect flaws in :

- Building materials
- Transport
- Aeronautics
- Aerospace

Most common techniques :

- Visual inspection
- **Ultrasonic waves**
- **Eddy currents**
- Thermography



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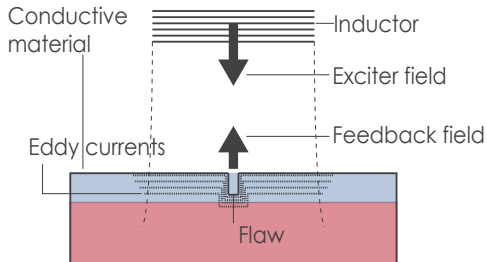
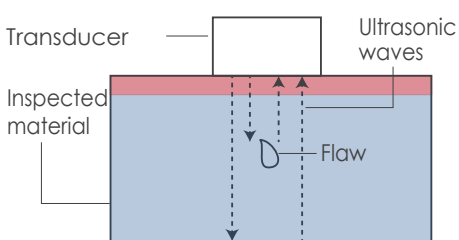
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The aim of this work is to combine both **ultrasonic and eddy current testing** using data fusion algorithms in order to detect flaws in a more reliable way



Data fusion is the combination of information from different sources in order to obtain information more accurate, reliable and at lower cost.

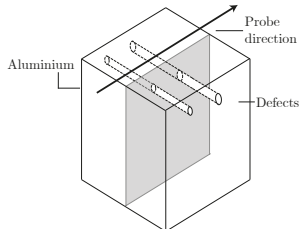
Why a data base is needed ?

- Obtain **ultrasonic and eddy current data from the same defects** to study the complementary of these techniques
- Use those data to develop and test **data fusion algorithms**
- Develop **inversion algorithms** with or without data fusion

How to obtain these data ?

- Through experimentation
 - ▶ Limited number of cases
- Simulated inspections
 - ▶ Control over data and defects :
256 cylindrical defects from 0.5 to 8 mm depth and radius by 0.5 mm step

Simple cases : homogeneous aluminum blocks with simple defect geometries



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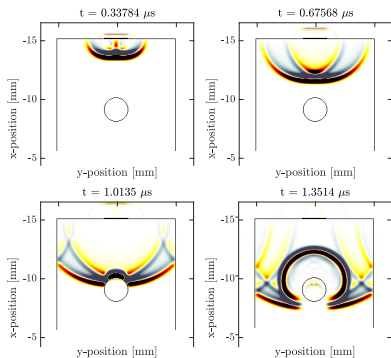
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Open source toolbox : **Mechanical wave propagation** ^[1] through pseudo-spectral finite difference method

- Homogeneous and isotropic medium
- Longitudinal waves



Transducer

- Radius of 6.35 mm (0.25 in)
- One measure each 5 mm

Signal

- $F = 5 \text{ MHz}$, $\lambda = 1.2 \text{ mm}$
- Five cycles pulses

Material

- Aluminum block
- 6400 m.s^{-1} longitudinal wave speed

Grid

- 24 points per wavelength
- 20 samples per period

1. TREEBY, B., COX, B. et JAROS, J., *k-Wave, A MATLAB toolbox for the time domain simulation of acoustic wave field*, 2012

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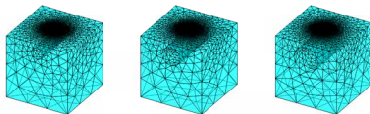
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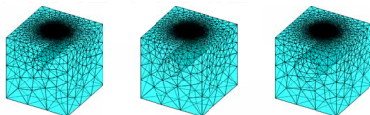
Finite element method calculations : Quasi-static electromagnetic waves

■ Two complementary formulations $A-\varphi$ and $T-\Omega$ [2]

D = 0.5 and R = 1 mm D = 0.5 and R = 1.5 mm D = 0.5 and R = 2 mm



D = 2 and R = 1 mm D = 2 and R = 1.5 mm D = 2 and R = 2 mm



Coil

- Radius of 4 mm
- 250 spires
- One measurement each 5 mm

Signal

- $F = 1 \text{ kHz}$, $\delta = 2 \text{ mm}$
- Excitation $I_{eff} = 1 \text{ A}$

Mesh

- 80000 elements
- Maximal density near the coil

Material

- Aluminum block
- Conductivity 37.7 MS/m
- $\mu_r = \epsilon_r = 1$

2. HENNERON, T., « Contribution à la prise en compte des Grandeurs Globales dans les Problèmes d'Electromagnétisme résolu avec la Méthode des Eléments Finis », thèse de doct., Université Lille1 - Sciences et Technologies, 2004

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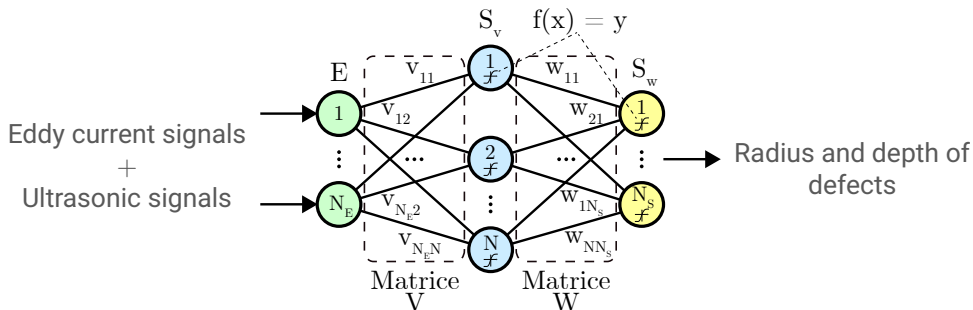
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Feed Forward Neural Network (FFNN)

- It can **approximate complex functions** [3]
- **No need for analytic or experimental model**
- It needs a learning data-set



3. RUMELHART, D. E., HINTON, G. E. et WILLIAMS, R. J., « Learning internal representations by error propagation », n^o V, 1985.

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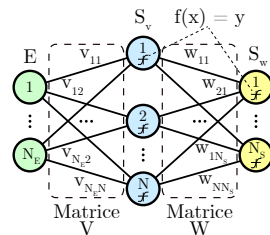
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- 33 inputs (3 features \times 11 positions)
- 10 hidden neurons
- 2 outputs (radius and depth predictions)



Parameters

- Activation functions **Tansig** and **Pureline** : $f_1(x) = \frac{2}{(1+e^{-2x})} - 1$ and $f_2(x) = ax + b$
- Optimization algorithm : **Bayesian regularization backpropagation** [4]
- Data base split : 70% training, 15% validation and 15% test

4. HAGAN, M. T., DEMUTH, H. B. et BEALE, M. H., « Neural Network Design », *Boston Massachusetts PWS*, t. 2, p. 734, 1995.

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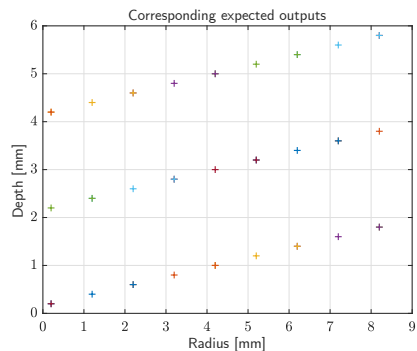
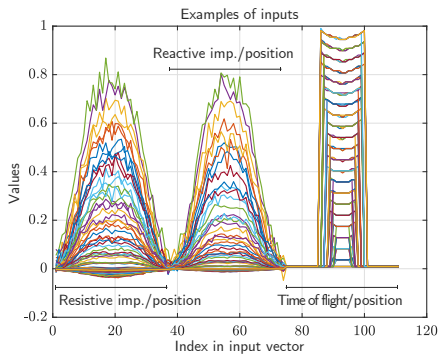
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Input data / Expected outputs

- Vector containing eddy current and ultrasonic data for each sensor position along inspected block \Rightarrow
 - Flaw radius
 - Flaw depth



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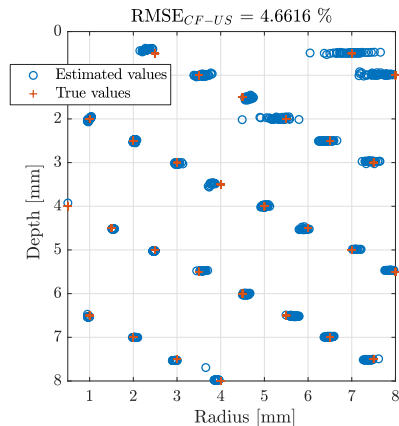
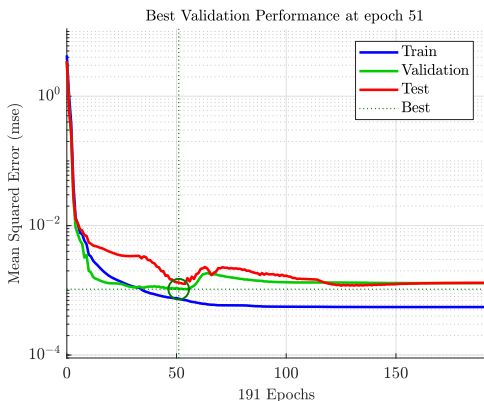
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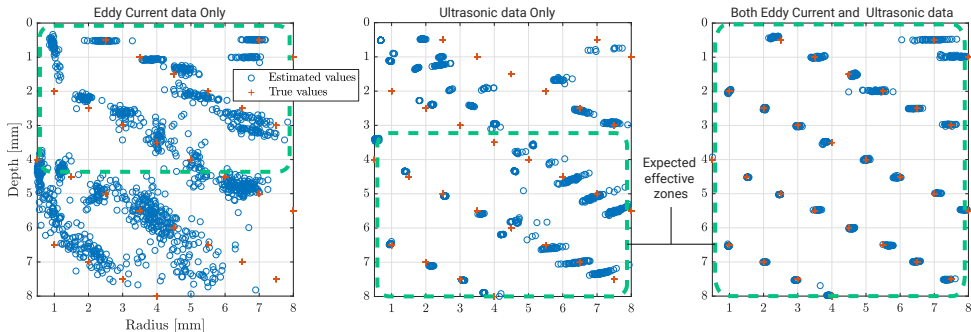
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- Network is trained with the training set (70%)
- Validation set (15%) allows to keep best prediction capabilities
- Performances of the network are computed with test set (15%) : **RMSE < 5 %**



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Results obtained on test data using neural networks trained with :
eddy current data only, ultrasonic data and the data fusion US-ED



■ Complementarity inspection methods

- ▶ Eddy current : Skin effect limitation
- ▶ Ultrasonic testing : Near field limitation
- ▶ Both : Better predictions

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- Data fusion with multi-layers neural network
 - ▶ Allows to detect flaws in a more reliable way and in the all data-set range overcoming the limitations of ultrasonic waves and eddy currents

- Future work :
 - ▶ Testing the trained network using experimental data as input
 - ▶ Optimization algorithms to better fit experimental conditions
 - ▶ Investigating more complex materials

Thank you for your attention

